

## Tuesday

07:45 - 08:45	<b>Registration</b>
08:45 - 09:45	<b>Keynote Lecture by Randall D. Beer</b> The Dynamics of Brain-Body-Environment Systems: A Status Report
09:45 - 10:05	<b>Measuring Autonomy by Multivariate Autoregressive Modelling</b> Anil Seth
10:05 - 10:25	<b>An Analysis of Behavioral Attractor Dynamics</b> Alberto Montebelli, Carlos Herrera, Tom Ziemke
10:25 - 10:45	<b>Coffee Break</b>
10:45 - 11:05	<b>The Dynamics of Associative Learning in an Evolved Situated Agent</b> Eduardo Izquierdo, Inman Harvey
11:05 - 11:25	<b>New Models for Old Questions: Evolutionary Robotics and the 'A not B' error</b> Rachel Wood, Ezequiel Di Paolo
11:25 - 11:45	<b>Adapting to Your Body</b> Peter Fine, Ezequiel Di Paolo, Eduardo Izquierdo
11:45 - 12:05	<b>Improving Agent Localisation Through Stereotypical Motion</b> Bart Baddeley, Andrew Philippides
12:05 - 12:45	<b>Poster Pitch</b>
12:45 - 14:15	<b>Lunch</b>
14:15 - 15:15	<b>Keynote lecture by Rudolf Bannasch</b> Morphological intelligence in bionic applications
15:15 - 15:35	<b>Near-Optimal Mobile Robot Recharging With The Rate-Maximizing Forager</b> Jens Wawerla, Richard Vaughan
15:35 - 15:55	<b>Evolving Virtual Neuronal Morphologies: a case study in Genetic L-Systems Programming</b> Benjamin Torben-Nielsen
15:55 - 16:55	<b>Poster Session and Coffee Break</b>
16:55 - 17:15	<b>Evolution of Neural Networks for Active Control of Tethered Airfoils</b> Allister Furey, Inman Harvey
17:15 - 17:35	<b>Feathered Flyer: Integrating Morphological Computation and Sensory Reflexes into a Physically Simulated Flapping-Wing Robot for Robust Flight Manoeuvre</b> YoonSik Shim, Phil Husbands
17:35 - 17:55	<b>Synthesizing Physically-Realistic Environmental Models from Robot Exploration</b> Josh Bongard
17:55 - 18:15	<b>Guided Self-organisation for Autonomous Robot Development</b> Georg Martius, J. Michael Herrmann, Ralf Der
18:15 - 19:30	<b>Panel Discussion</b>

	Keynote Lectures
	Talks
	Posters
	Panel Discussion